

Numerical optimization of tokamak and stellarator equilibrium

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Theory Department Research and Review Seminar

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Before we begin some background

- Funding levels (2015)
 - 70% W7-X collaboration
 - 20% NSTX-U/Theory partnership
 - 10% LDRD
- Leaving for W7-X for 9? months in March
- Things I'm not talking about today
 - VMEC Benchmarking
 - DIAGNO Benchmarking
 - SPEC ITER/DIII-D Calculations
 - W7-X Field line mapping experiments

Overview of my optimization work

- LHD Equilibrium Reconstruction
 - Initial work with STELLOPT and VMEC
 - Rewrite and validation of magnetic diagnostics code (DIAGNO)
 - MSE synthetic diagnostics into STELLOPT
- Tokamak 3D Equilibrium Reconstruction
 - Rewrite of STELLOPT (STELLOPTV2)
 - DIII-D Reconstruction (NE,TE,TI profile diagnostics)
 - ITER forward modeling of applied RMP's
- Turbulent Transport Optimization
 - Implementation of parallel GENE in STELLOPTV2
- Development of IPECOPT for NTV optimization on NSTX-U

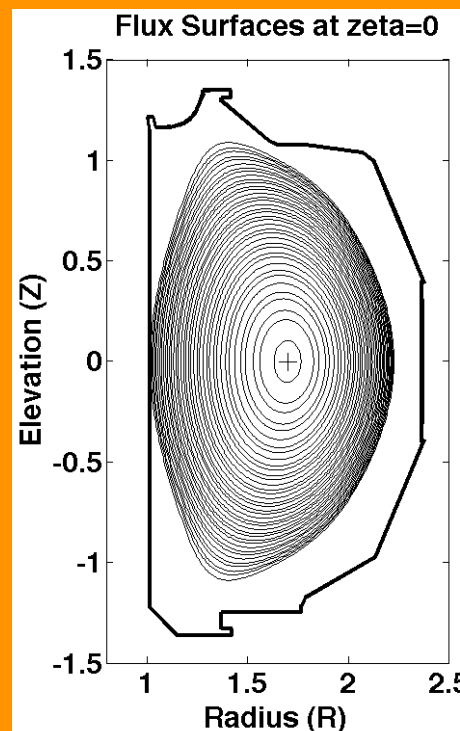
Optimization of equilibrium in a nutshell.

Input Parameters

- Currents
- Vacuum Fields
- Pressure, etc.

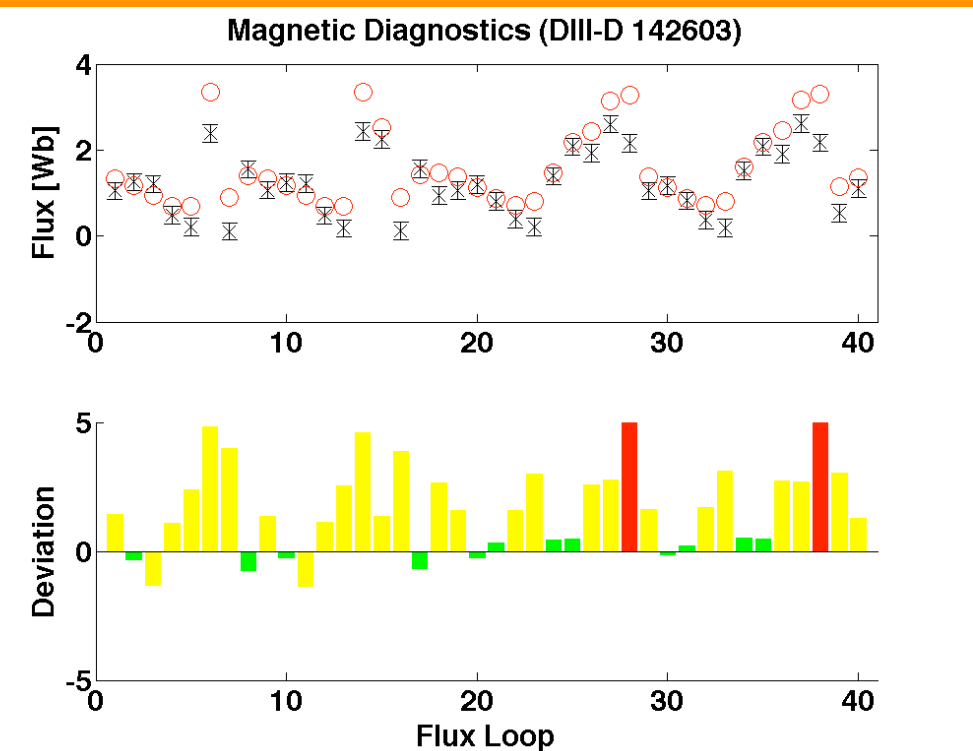
← These need to result in a good match to these.

Equilibrium Model



Synthetic Signals

Measurements



Mathematically how can this be achieved?

- Begin with some function we wish to minimize (optimize)

$y_j(p_i)$: Function

p_i : Parameters

- Given a set of parameters how do we choose better ones?

$$\tilde{p}_i = p_i + h_i$$

Mathematically how can this be achieved?

- Begin with some function we wish to minimize (optimize)

$y_j(p_i)$: Function

p_i : Parameters

In practice we minimize

$$\chi^2(p_i) = \sum_j \left| \frac{Y_j - y_j(p_i)}{\sigma_j} \right|^2$$

- Given a set of parameters how do we choose better ones?

$$\tilde{p}_i = p_i + h_i$$

Numerical optimization methods are numerous

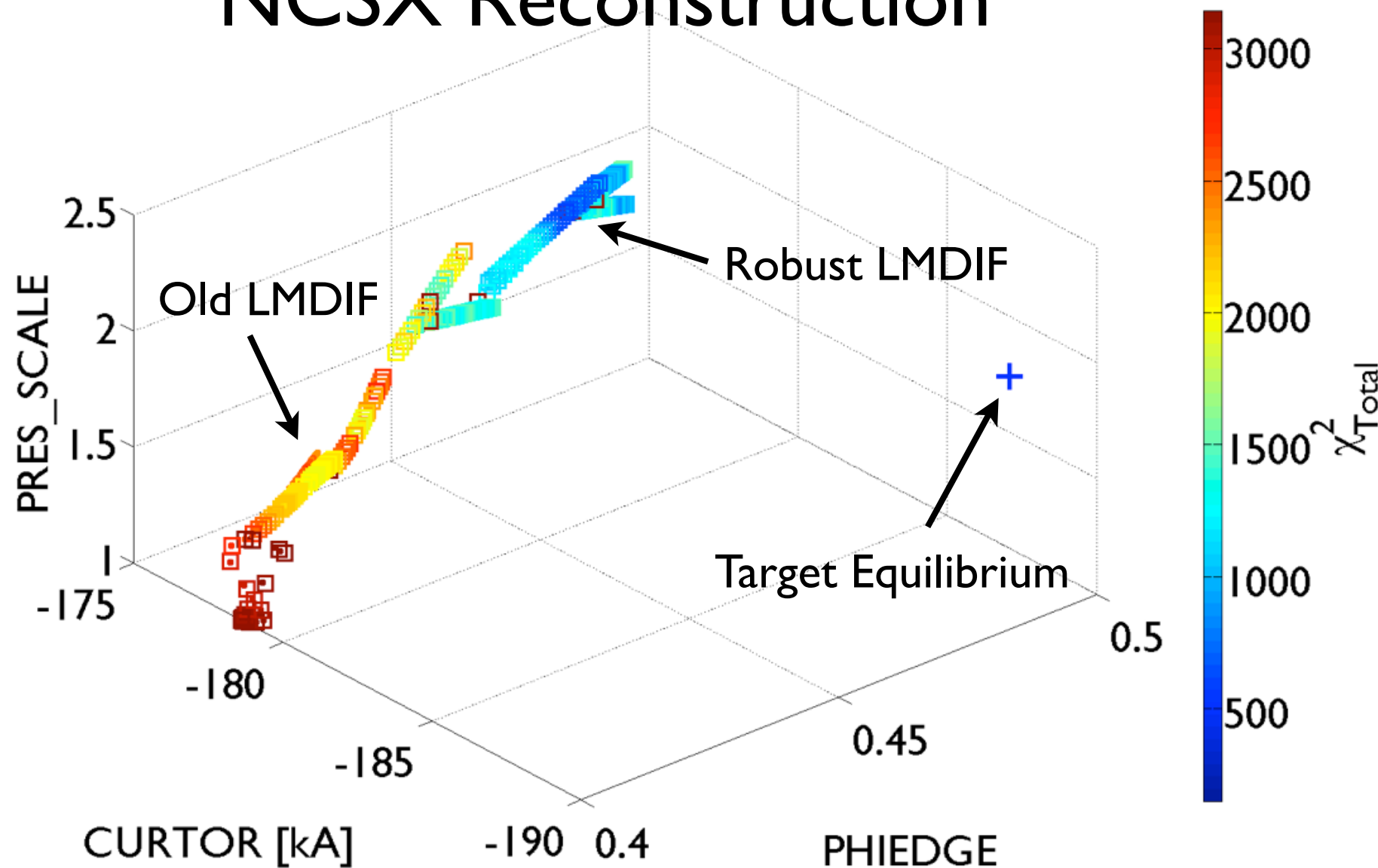
- Derivative Methods $\vec{p}_f = \vec{p}_0 + \vec{h}$
 - Gradient Descent $\vec{h}_{GD} = \alpha \tilde{J}^\dagger \tilde{W} (\vec{y}_{target} - \vec{y}(\vec{p}))$
 - Gauss Newton $\vec{h}_{GN} = [\tilde{J}^\dagger \tilde{W} \tilde{J}]^{-1} \tilde{J}^\dagger \tilde{W} (\vec{y}_{target} - \vec{y}(\vec{p}))$
 - Levenberg $\vec{h}_{LEV} = [\tilde{J}^\dagger \tilde{W} \tilde{J} + \lambda \tilde{I}]^{-1} \tilde{J}^\dagger \tilde{W} (\vec{y}_{target} - \vec{y}(\vec{p}))$
 - Levenberg-Marquardt $\vec{h}_{LEV-MAR} = [\tilde{J}^\dagger \tilde{W} \tilde{J} + \lambda \text{diag}(\tilde{J}^\dagger \tilde{W} \tilde{J})]^{-1} \tilde{J}^\dagger \tilde{W} (\vec{y}_{target} - \vec{y}(\vec{p}))$
- Genetic Algorithms
- Particle Swarm
- Simulated Annealing

The modified Levenberg-Marquardt

- Parallelized over Jacobian evaluation
- Scan over the Levenberg parameter
- STEP_OPT procedure if Jacobian evaluation yields better results than Levenberg step (M. Zarnstorff)
- Failed Jacobian directions removed from the analysis (Robust Jacobian)

Robust Jacobian improves fit

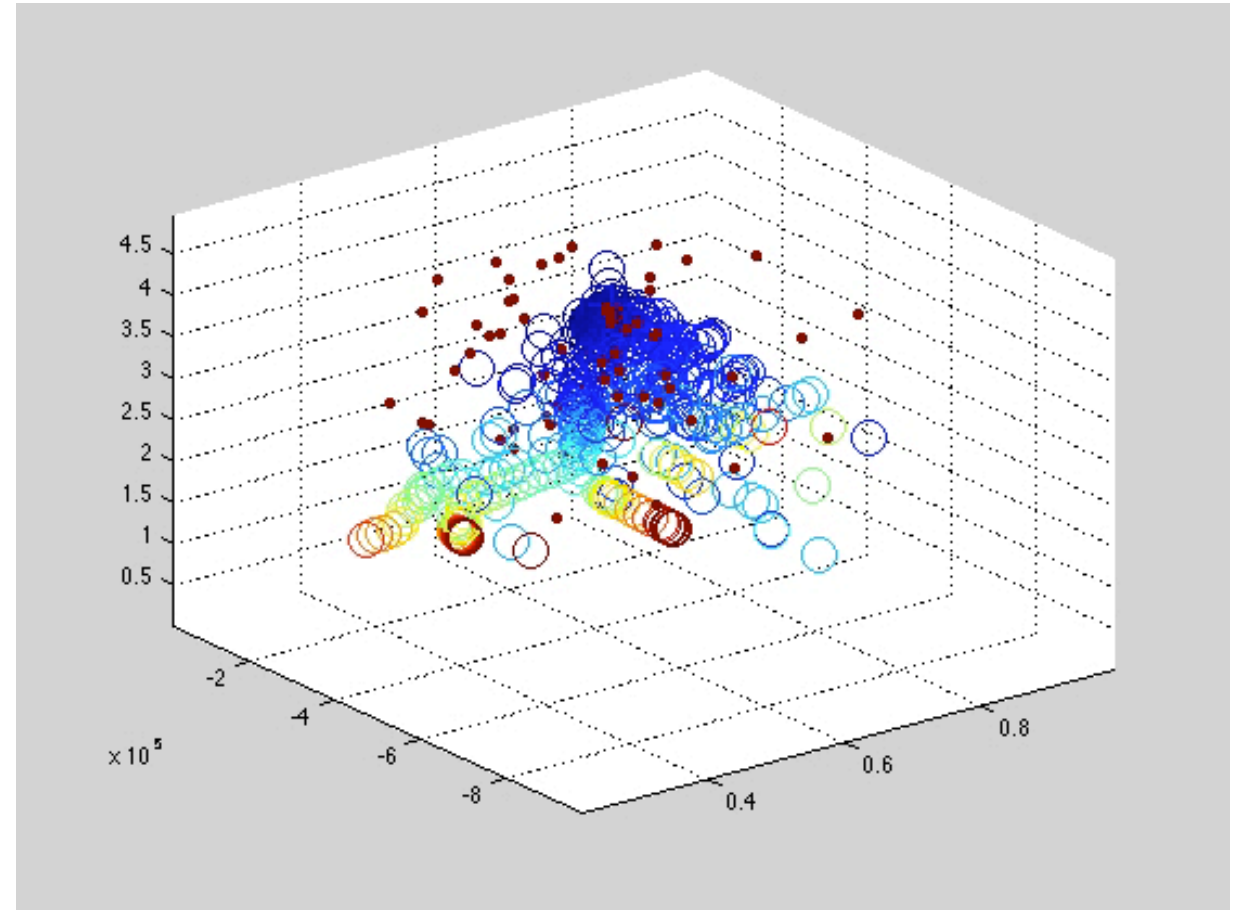
NCSX Reconstruction



Approximately 1/2 of function evaluations forced to fail.

Particle Swarm Optimization (PSO)

- Initial random distribution of points in the parameter hyperspace.
- Each particle has a unique velocity through hyperspace.
- Each particle has a record of its best solution
- All particles keep track of the overall best solution found



Velocity Equation

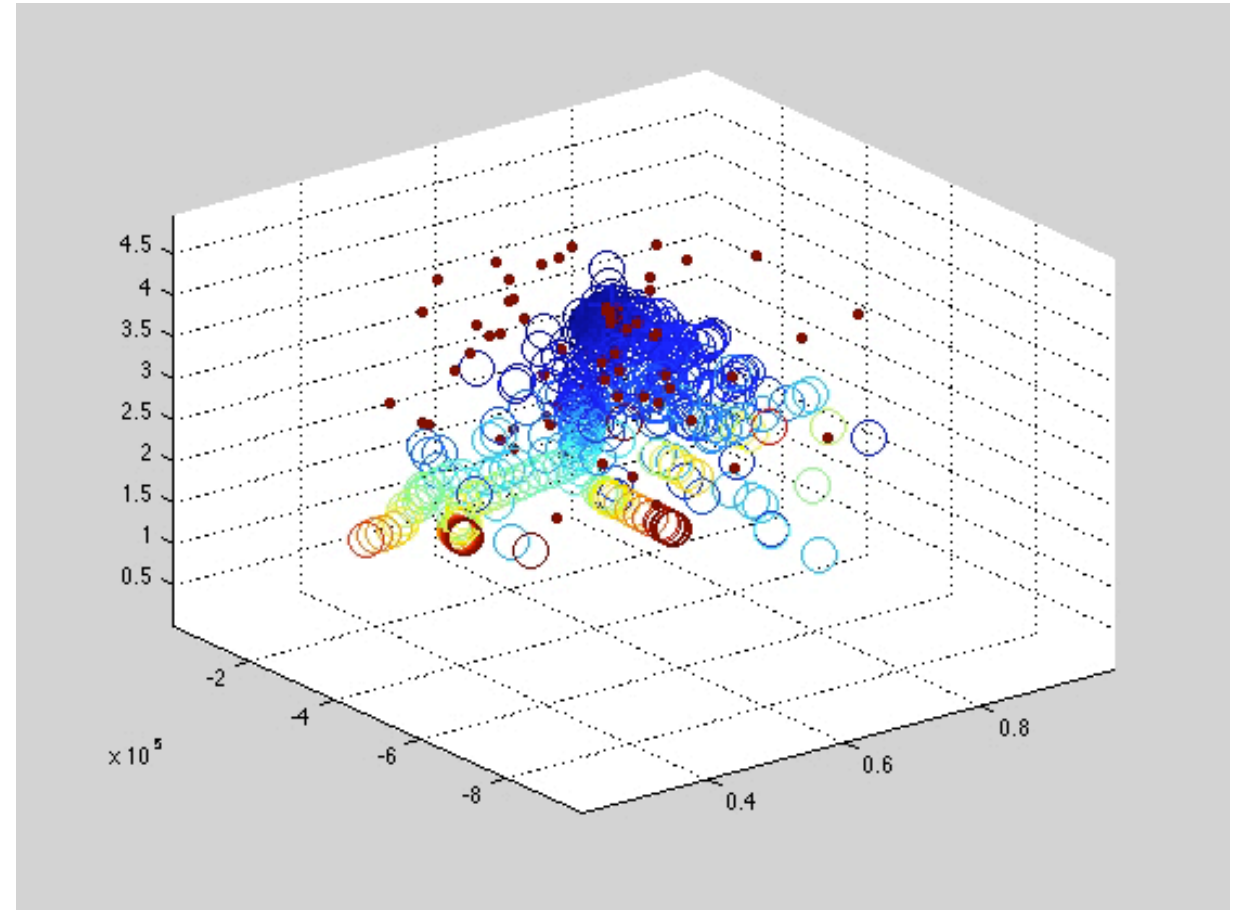
$$\vec{v}_i^{new} = \vec{v}_i + C_1 \left(\vec{x}_i^{best} - \vec{x}_i \right) + C_2 \left(\vec{x}_{global}^{best} - \vec{x}_i \right)$$

Position Update

$$\vec{x}_i^{new} = \vec{x}_i + \vec{v}_i$$

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Velocity Equation

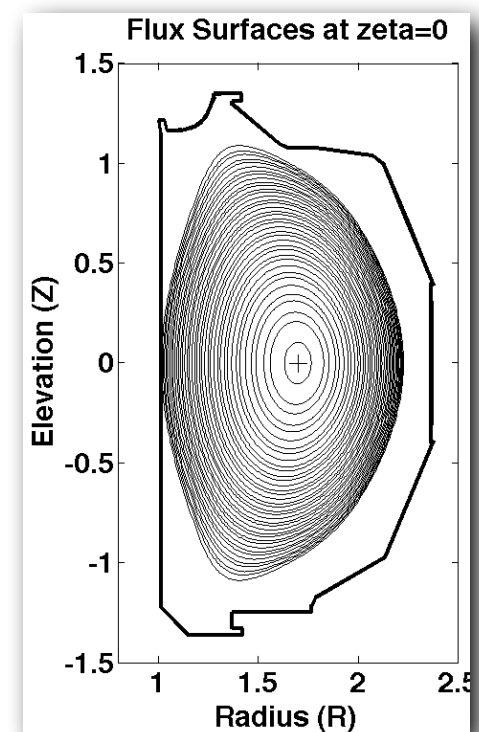
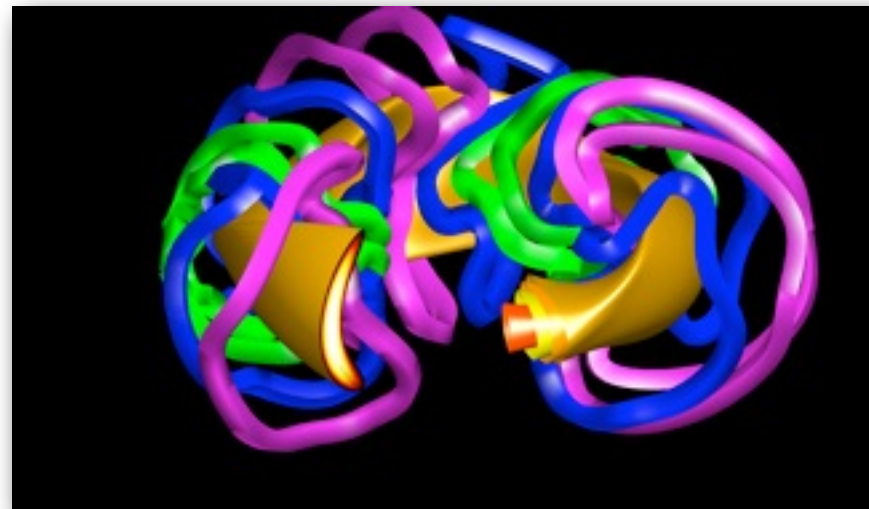
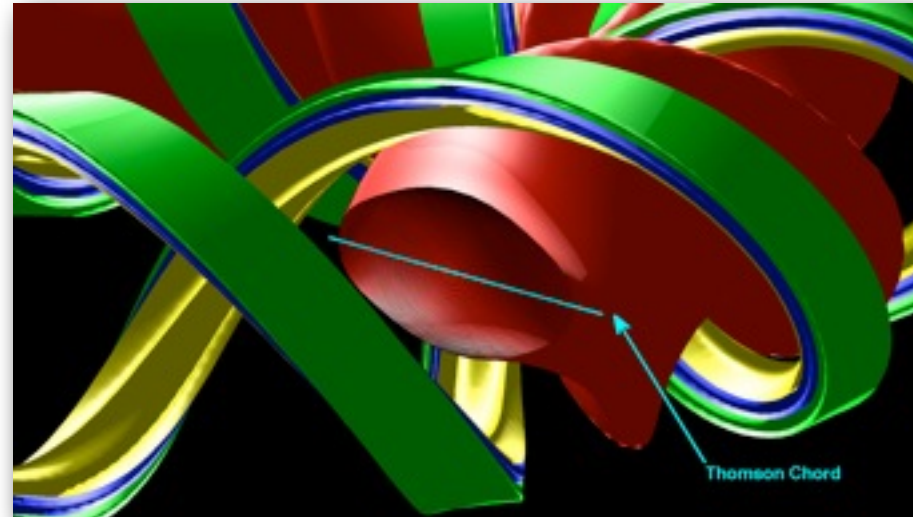
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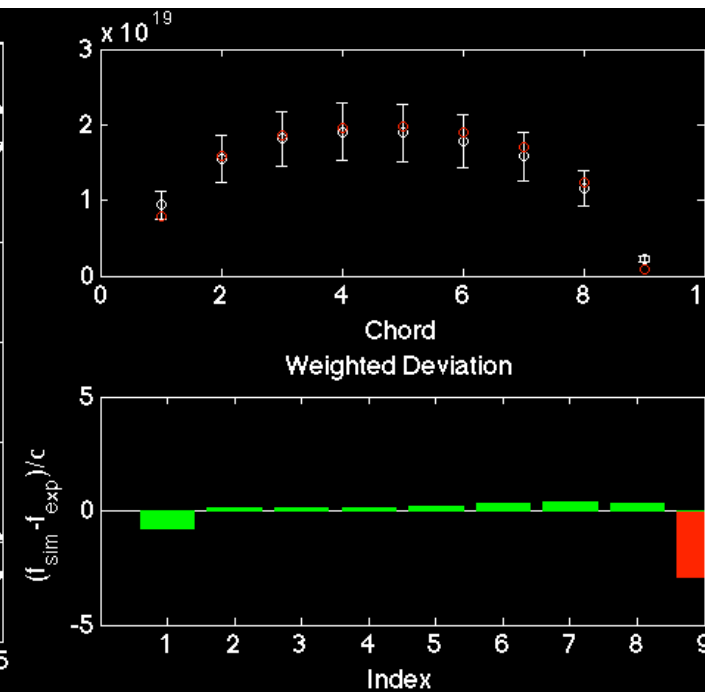
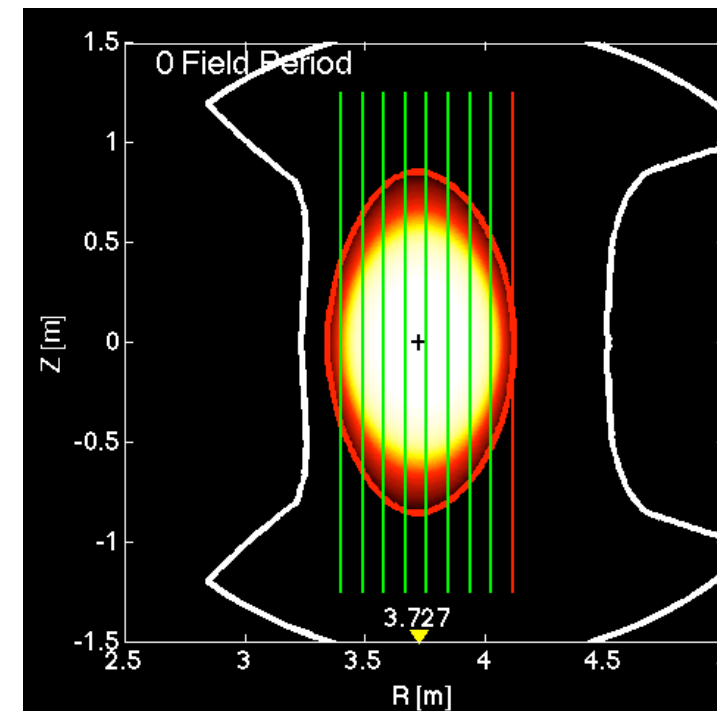
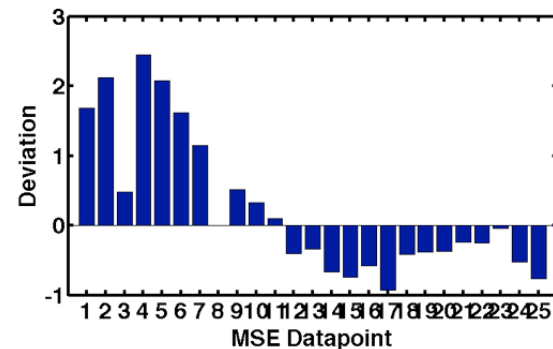
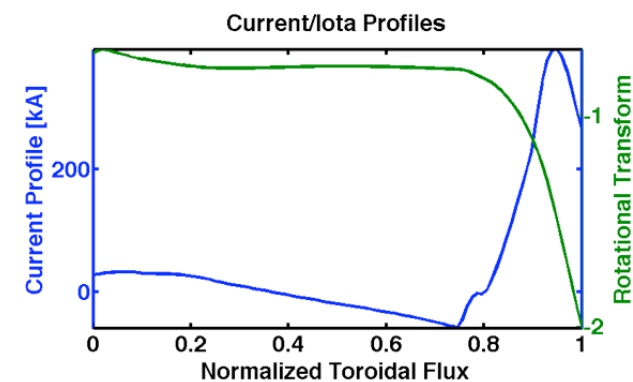
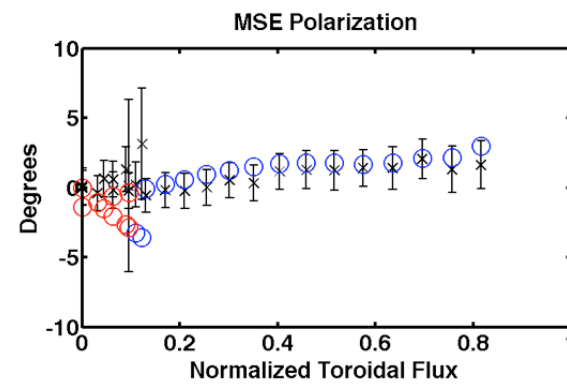
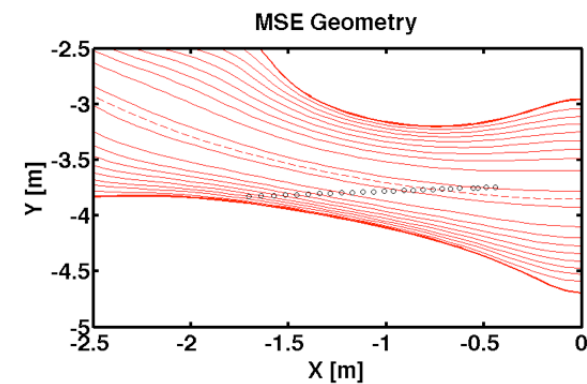
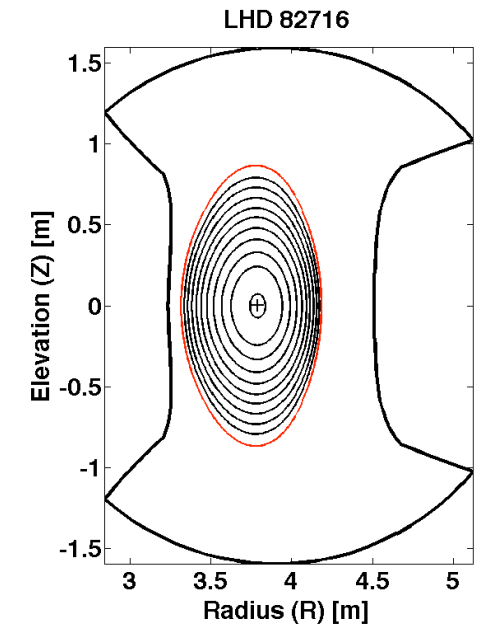
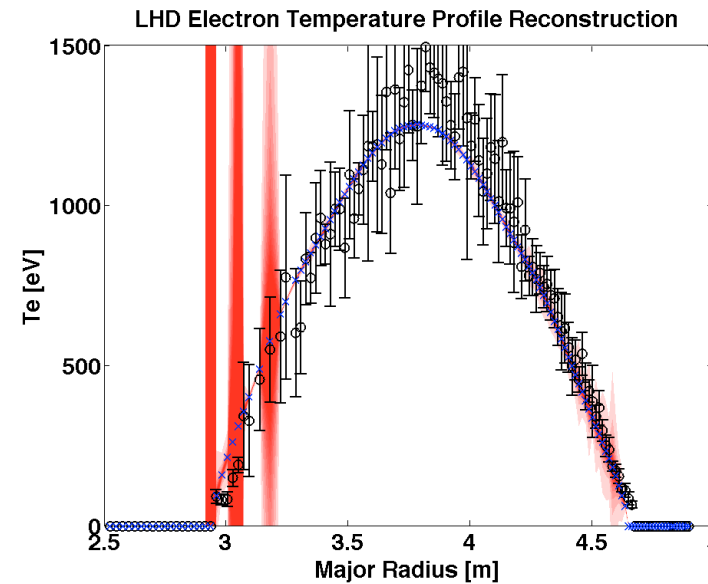
STELLOPT fits a VMEC equilibrium to targets

- Optimization Studies
 - Global Stability
 - Turbulent Transport
- Experimental Design
 - HSX, CTH, NCSX
- Reconstruction
 - W7-AS, LHD, DIII-D



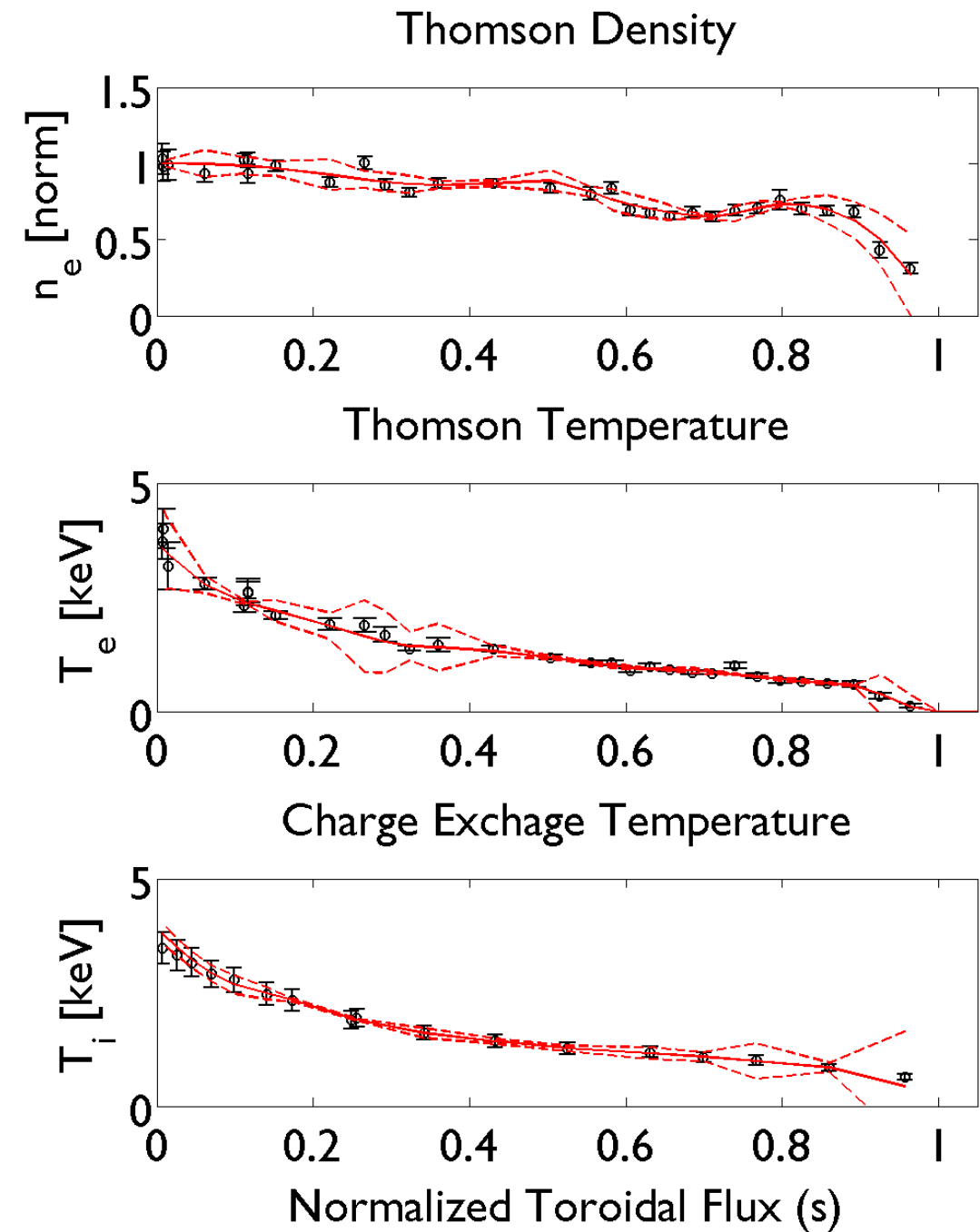
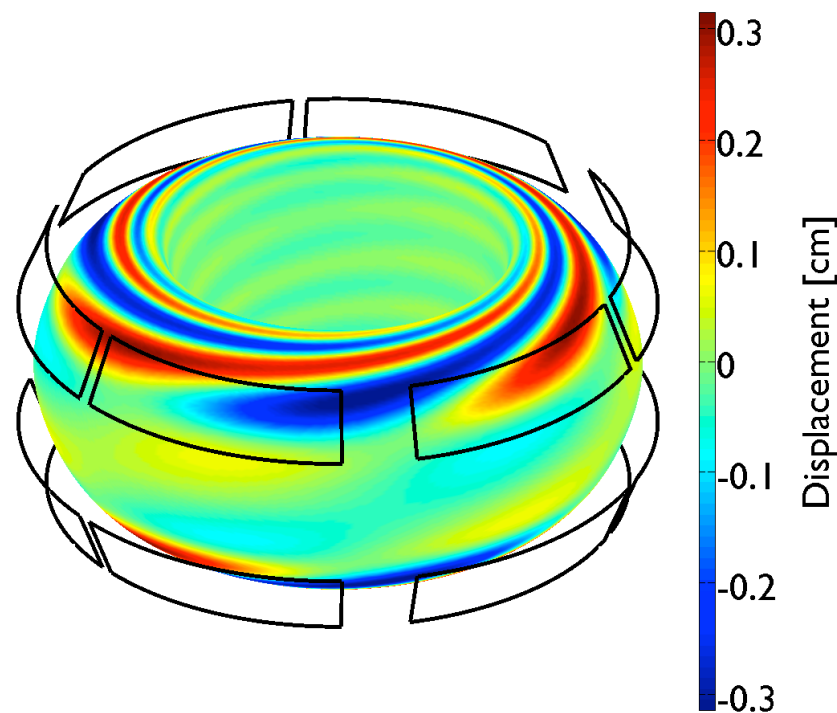
LHD Equilibrium Reconstruction

- Free boundary 3D equilibrium fit to
 - Thomson
 - Interferometry
 - MSE



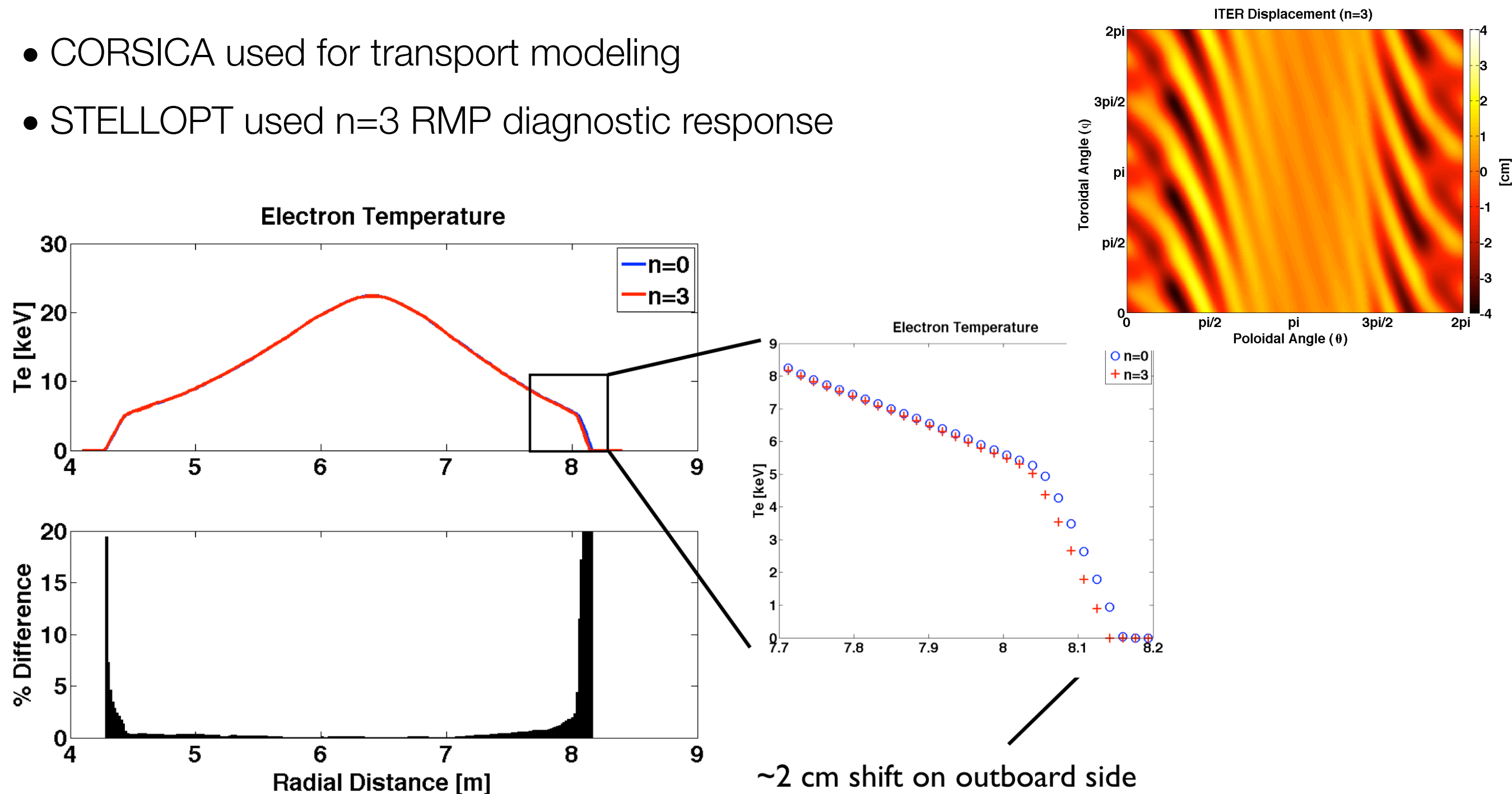
DIII-D 3D Equilibrium Reconstruction

- Free boundary 3D ($n=3$) equilibrium fit to
 - Magnetics
 - Thomson
 - Charge Exchange
 - Interferrometry
 - MSE



Forward modeling of ITER diagnostic response

- CORSICA used for transport modeling
- STELLOPT used $n=3$ RMP diagnostic response



Turbulent transport optimization of stellarators

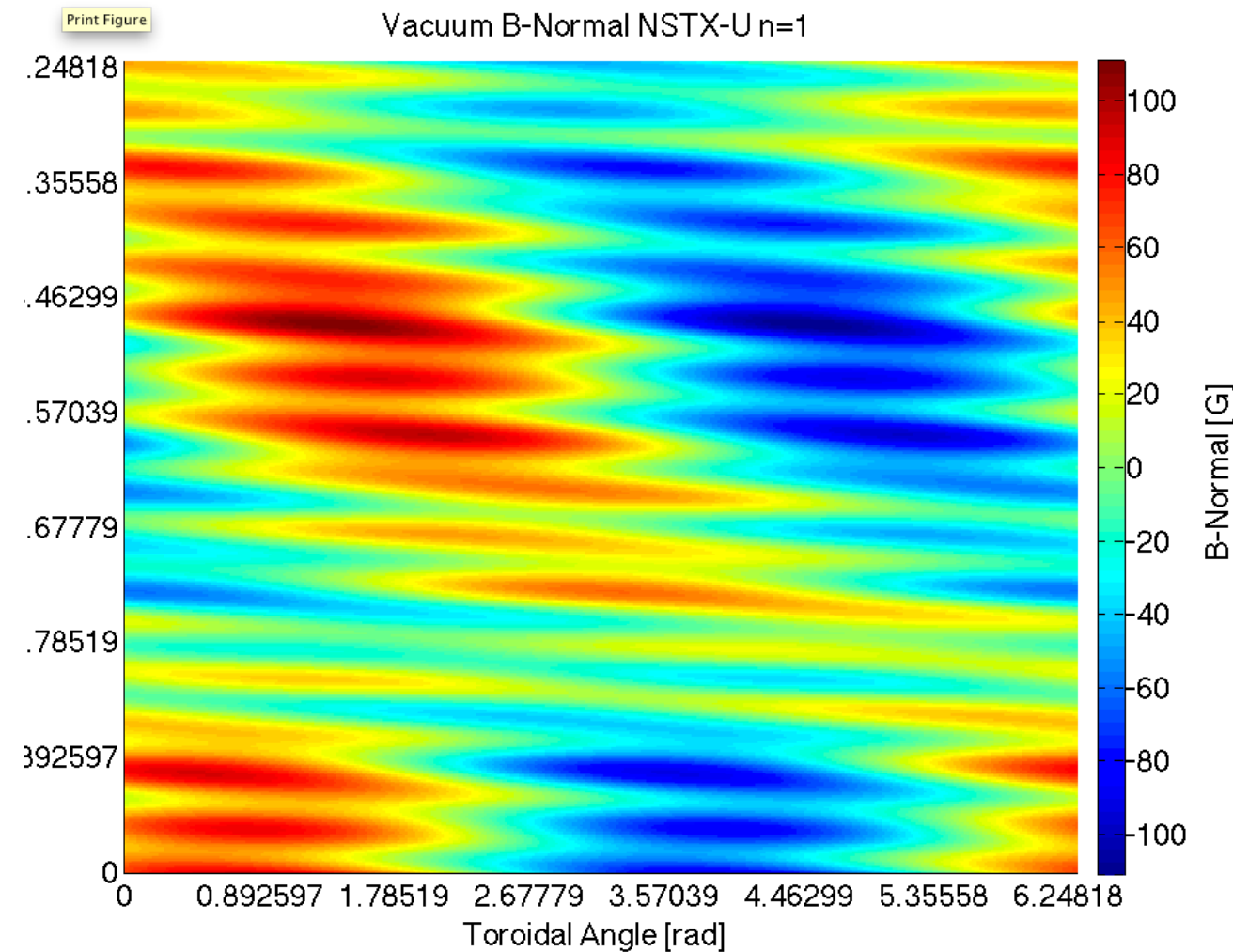
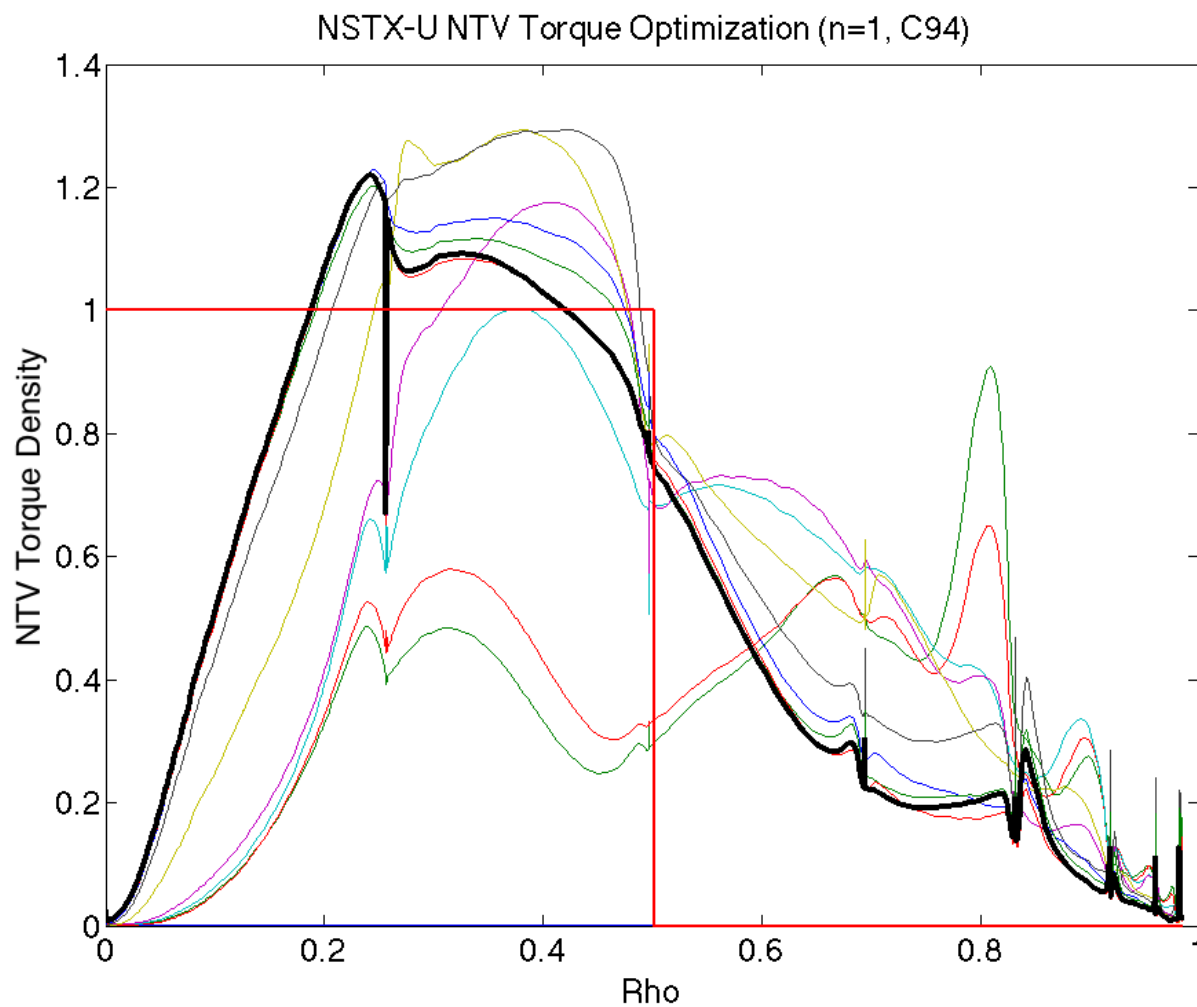
- The capability to optimize stellarators for reduced ITG and TEM turbulence has been demonstrated (Mynick, Pomphrey, Helander, Proll, Xanthopolous)
- The turbulent proxies have been included in STELLOPTV2
- Work is ongoing to incorporate parallel linear GENE into STELLOPTV2
- W7-X should allow validation

An IPEC based optimization code has been developed

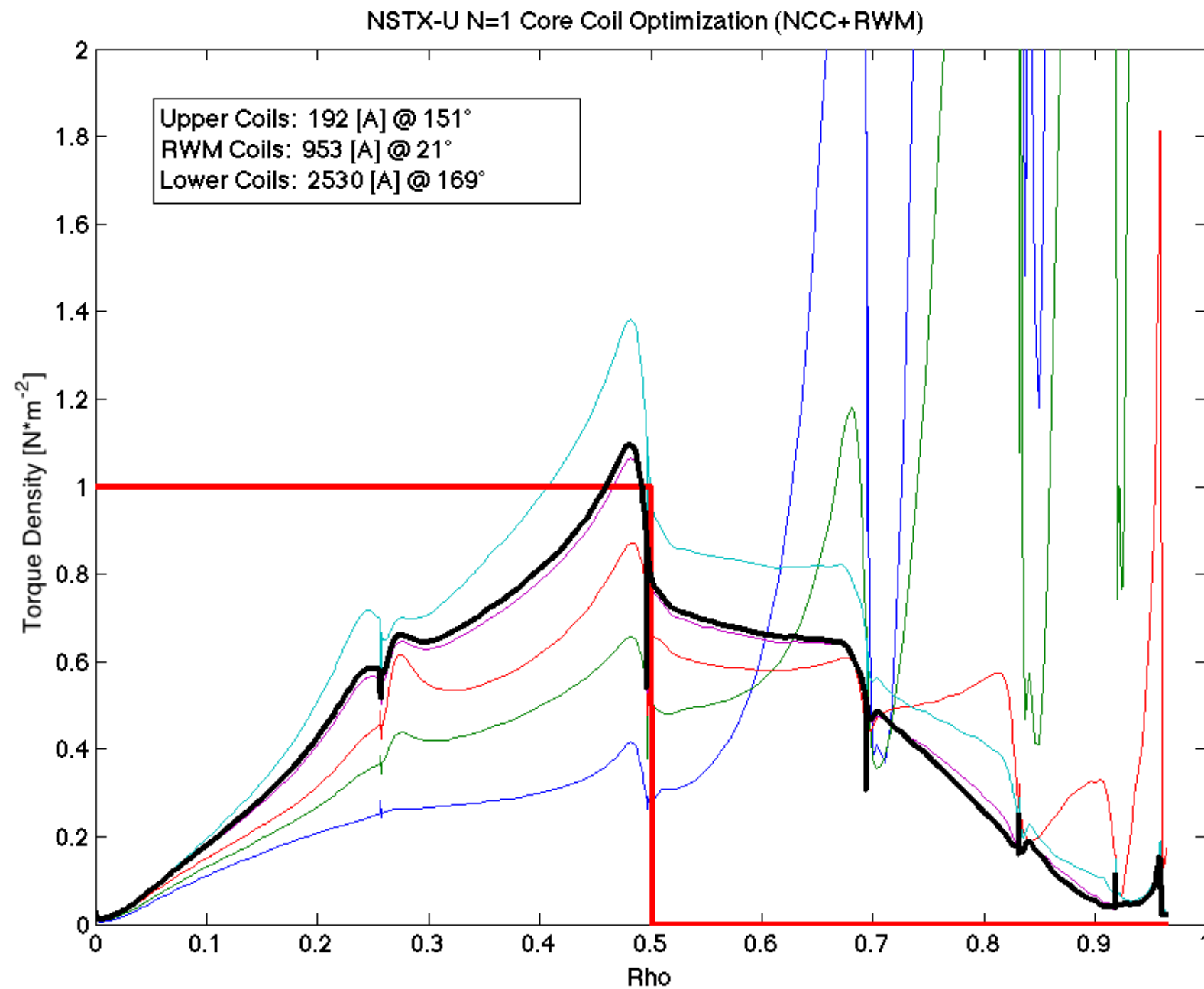
- Calculates a least squares fit of IPEC input parameters to target physics parameters
 - Based on STELLOPT
 - Multiple optimization techniques
 - Targeting NTV torque as calculated by PENT
 - Fixed and free boundary optimizations
 - Coil currents can be directly optimized

NSTX-U Core Torque Optimization

- An applied vacuum B-normal spectrum was optimized
 - Core Torque targeting (~ 0.5 [N.m])
 - $n=1$ spectrum

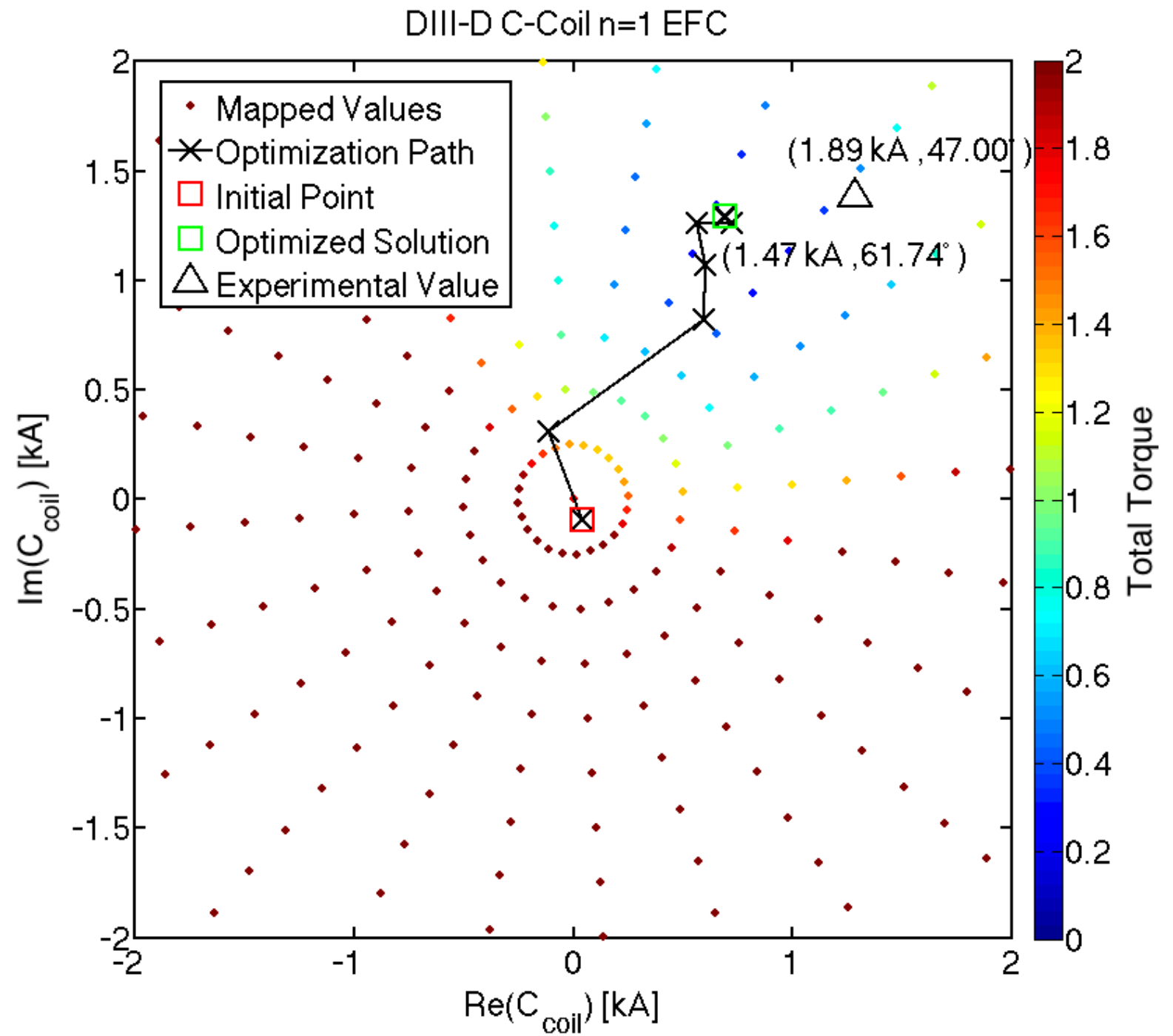
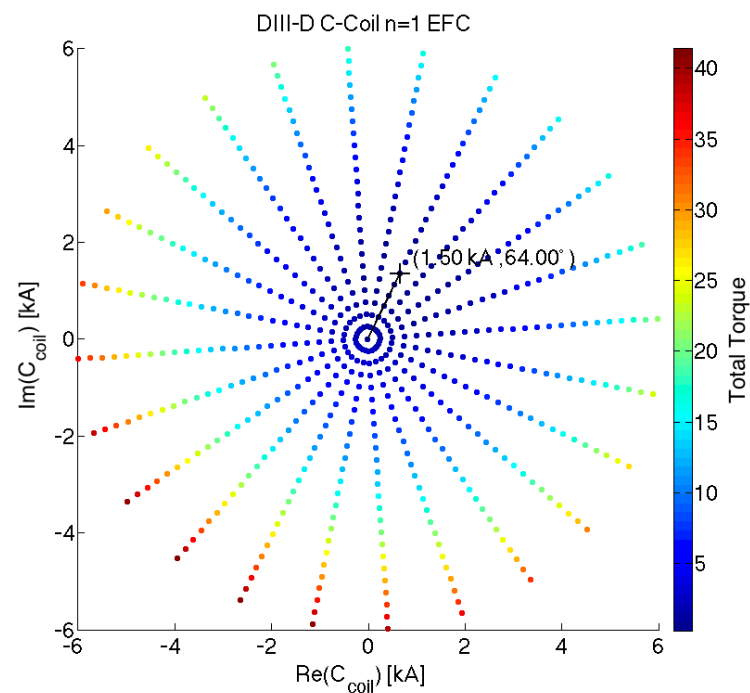


RWM+NCC coil optimization



DIII-D error field experiments used to validate

- DIII-D C-coil rotation scan experiments
 - C-coil phase and amplitude scan performed (2D parameter space)
 - Optimizer used for similar experiment (SURFMN error field)



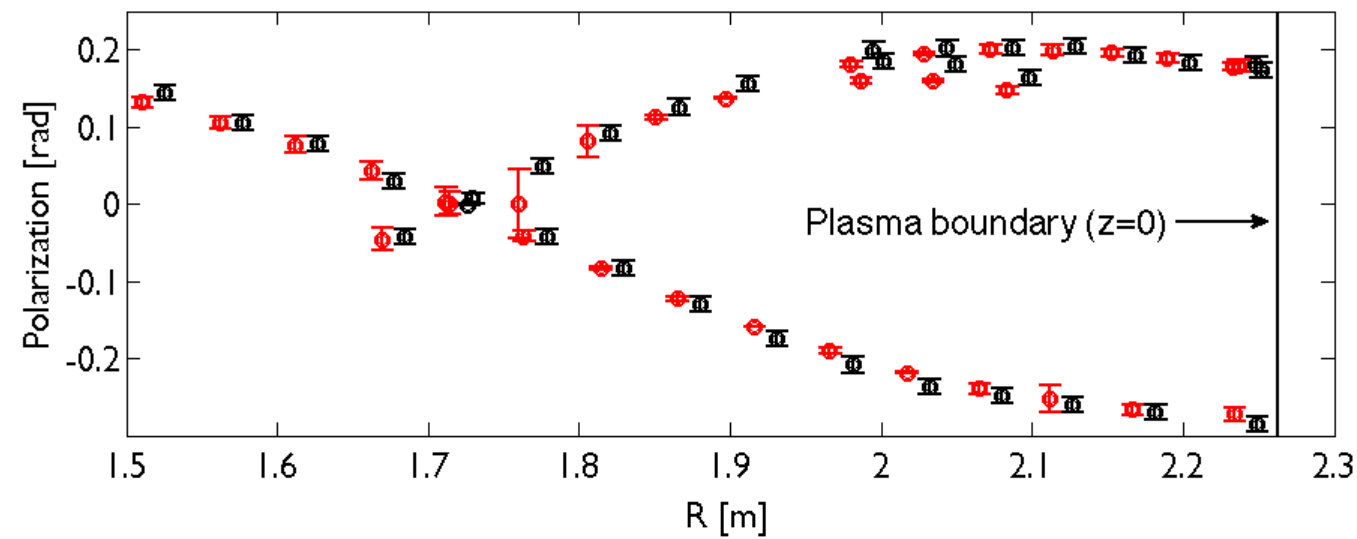
Short term plans (next year)

- Publish IPECOPT results (PPCF)
- Implement 3D equilibrium reconstruction on W7-X
- STELLOPT/GENE runs on Hydra/Hopper
- Energetic particle optimization in STELLOPT

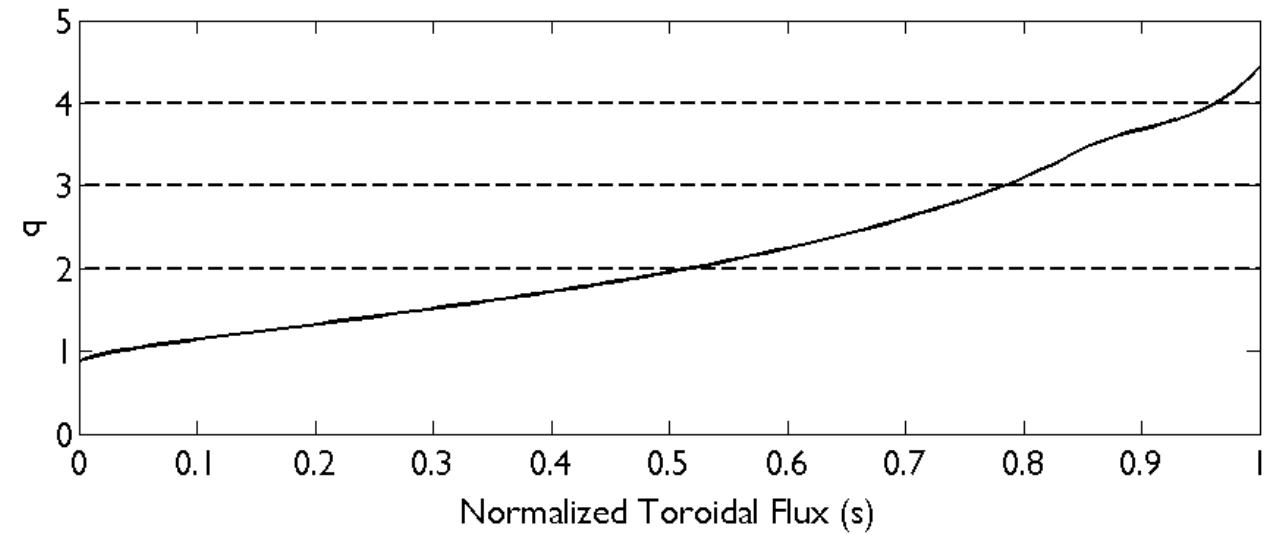
Additional Slides

DIII-D MSE Fit

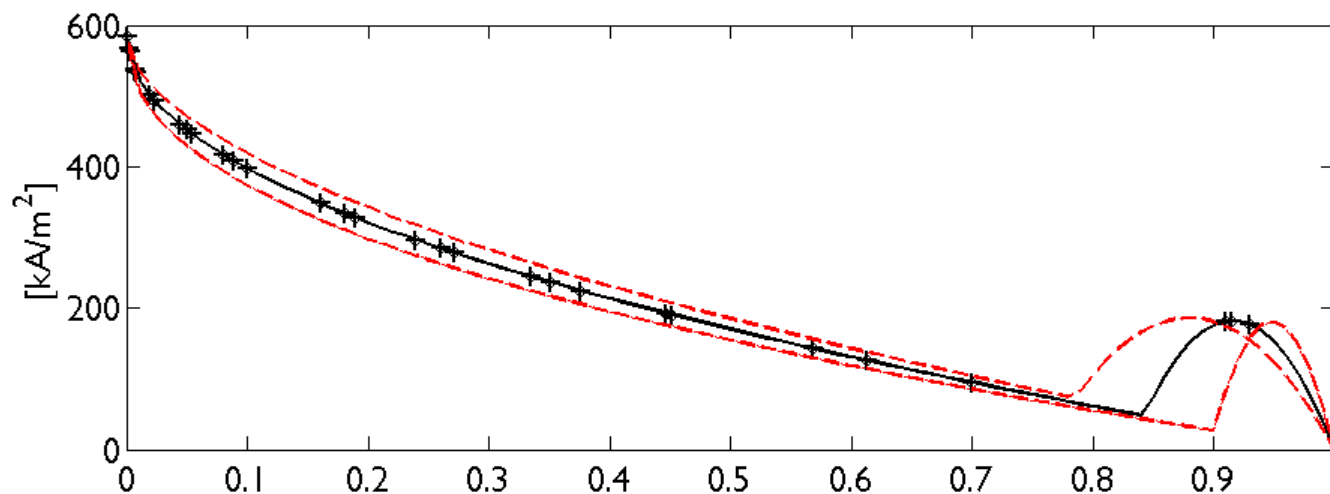
MSE Polarimetry



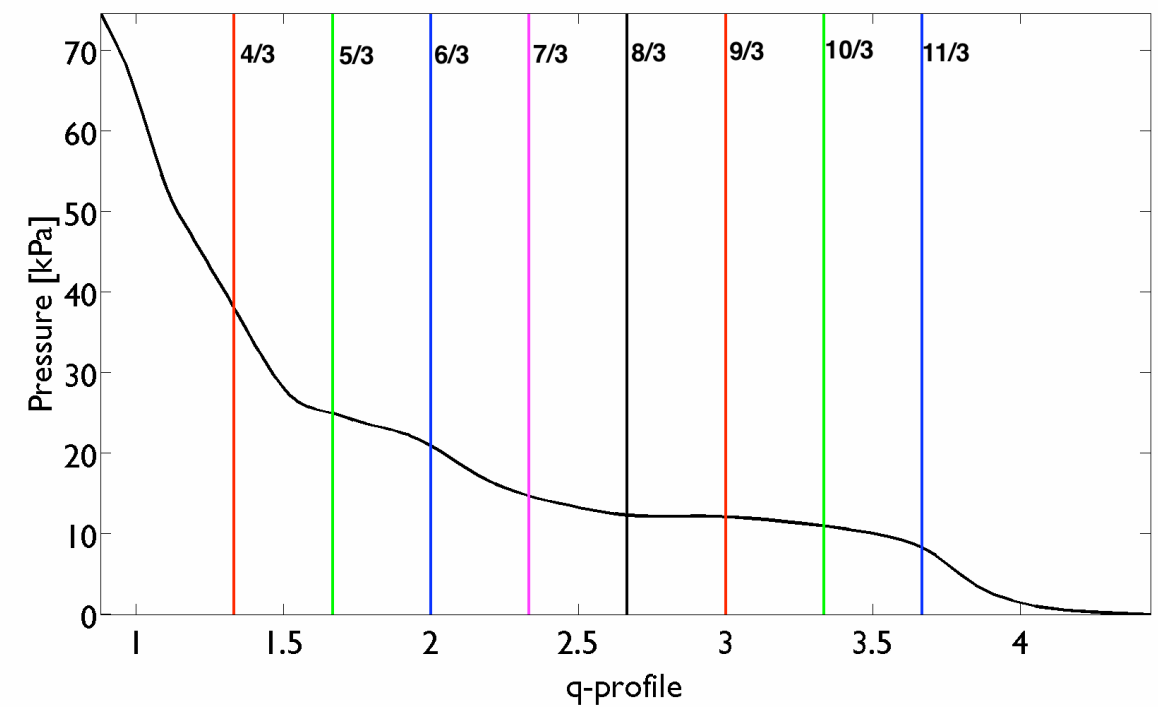
Safety Profile (q)



Reconstructed Current Profile



DIII-D profile comparison (shot 142603)



DIII-D Magnetics

